INTERNATIONAL STANDARD

ISO 20663

First edition
2020-01

Ships and marine technology — Grab dredger supervisory and control systems

Reference number
ISO 20663:2020(E)

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Published in Switzerland

Contents

Page

Foreword ..... **iv**
Introduction ..... **v**
1 Scope **1**
2 Normative references **1**
3 Terms , definitions and abbreviated terms **1**
3.1 Terms and definitions 1
3.2 Abbreviated terms 2
4 Components and structure **2**
4.1 Components 2
4.2 Structure 2
5 General requirements **2**
5.1 Operating position and control mode 2
5.1.1 Operating position 2
5.1.2 Control mode 2
5.2 External communication 2
5.3 Diagnostic 3
5.4 HMI graphics 3
5.4.1 Alarm level 3
5.4.2 Conventions on graphic colours 3
5.4.3 Brightness of the HMI 3
6 Functional requirements **4**
6.1 SCADA 4
6.1.1 General description 4
6.1.2 Pontoon positioning 4
6.1.3 Crane movement 4
6.1.4 Grab operation 4
6.1.5 Calibration of system 5
6.2 DPM 5

Foreword

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This document was prepared by Technical Committee ISO/TC 8, *Ships and marine technology.*

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

This document describes the supervisory and control system for a number of components, functions and systems that can, but do not have to, be installed on board of a grab dredger. It does not prescribe that all described components, functions and systems need to be installed.

Ships and marine technology — Grab dredger supervisory and control systems

1 Scope

This document specifies the components and structure, general requirements, and functional requirements of grab dredger supervisory and control systems.

It is applicable only to the installed components, functions or systems. It covers the design, manufacture and modifications.

2 Normative references

The following referenced documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 8384, *Ships and marine technology — Dredgers — Vocabulary*

3 Terms , definitions and abbreviated terms

3.1 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 8384 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

— ISO Online browsing platform: available at https://www.iso.org/obp

— IEC Electropedia: available at http://www.electropedia.org/

3.1.1
grab dredger supervisory and control system
GD-SCS
system used for supervising and controlling the operations of a grab dredger

3.1.2
dredging profile monitor
DPM
system used to accurately measure and monitor the grab dredger's position and heading, and the grab bucket's position and depth, via plane view and profile view

3.1.4
opening value
value of opening of the grab bucket, expressed in percent (%), where 0 % means closed and 100 % means fully opened