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Third edition
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Intelligent transport systems — Adaptive cruise control systems — Performance requirements and test procedures

Systèmes intelligents de transports — Systèmes stabilisateurs de vitesse adaptés — Exigences de performance et modes opératoires

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation on the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 204, *Intelligent transport systems*.

This third edition of ISO 15622 cancels and replaces ISO 15622:2010 and ISO 22179:2009, which have been technically revised.

The main changes compared to the previous editions are as follows:

— the third edition of ISO 15622 is extended with the performance requirements and test procedures for full speed range adaptive cruise control systems formerly described in ISO 22179:2009 (with minor changes);

— in-vehicle devices are allowed as a possible source for the acquisition of driver commands (set-speed-advise);

— curve classification and related dependencies have been removed;

— automatic start from hold is no longer prohibited.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

The main system function of Adaptive Cruise Control (ACC) is to control vehicle speed adaptively to a forward vehicle by using information about: (1) distance to forward vehicles, (2) the motion of the subject (ACC equipped) vehicle and (3) driver commands (see Figure 1). Based upon the information acquired, the controller (identified as "ACC control strategy" in Figure 1) sends commands to actuators for carrying out its longitudinal control strategy and it also sends status information to the driver. Optionally, the driver may choose to have the ACC use set speed advice from in-vehicle devices.

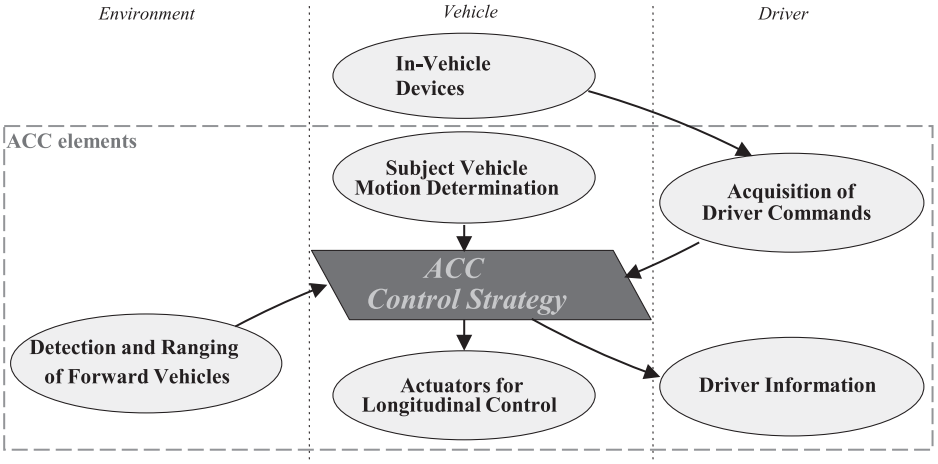

Figure 1 — Functional ACC elements

The goal of ACC is a partial automation of the longitudinal vehicle control and the reduction of the workload of the driver with the aim of supporting and relieving the driver in a convenient manner. The generic ACC system comprehends two classes: Full Speed Range ACC (FSRA) and Limited Speed Range ACC (LSRA).

This document can be used as a system level standard by other standards, which extend the ACC to a more detailed standard, e.g. for specific detection and ranging sensor concepts or higher level of functionality. Therefore, issues like specific requirements for the detection and ranging sensor function and performance or communication links for co-operative solutions will not be considered here.

Intelligent transport systems — Adaptive cruise control systems — Performance requirements and test procedures

1 Scope

This document contains the basic control strategy, minimum functionality requirements, basic driver interface elements, minimum requirements for diagnostics and reaction to failure, and performance test procedures for Adaptive Cruise Control (ACC) systems.

ACC systems are realised as either Full Speed Range Adaptive Cruise Control (FSRA) systems or Limited Speed Range Adaptive Cruise Control (LSRA) systems. LSRA systems are further distinguished into two types, requiring manual or automatic clutch. Adaptive Cruise Control is fundamentally intended to provide longitudinal control of equipped vehicles while travelling on highways (roads where non-motorized vehicles and pedestrians are prohibited) under free-flowing and for FSRA-type systems also for congested traffic conditions. ACC can be augmented with other capabilities, such as forward obstacle warning. For FSRA-type systems the system will attempt to stop behind an already tracked vehicle within its limited deceleration capabilities and will be able to start again after the driver has input a request to the system to resume the journey from standstill. The system is not required to react to stationary or slow moving objects

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 2575, *Road vehicles — Symbols for controls, indicators and tell-tales*

UN/ECE Regulation No. 13-H. Uniform provisions concerning the approval of passenger cars with regard to braking

3 Terms and definitions

For the purpose of this document, the following terms and definitions apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

— IEC Electropedia: available at http://www.electropedia.org/

— ISO Online browsing platform: available at http://www.iso.org/obp

3.1
active brake control
function that causes application of the brake(s), not applied by the driver, in this case controlled by the ACC system

3.2
Adaptive Cruise Control
ACC
enhancement to conventional cruise control systems [see *conventional cruise control* (3.5)], which allows the subject vehicle to follow a forward vehicle at an appropriate distance by controlling the engine and/or power train and potentially the brake