# BS EN 61851-23:2014

Incorporating corrigendum May 2016



**BSI Standards Publication** 

# Electric vehicle conductive charging system

Part 23: DC electric vehicle charging station (IEC 61851-23:2014)



#### **National foreword**

This British Standard is the UK implementation of EN 61851-23:2014. It is identical to IEC 61851-23:2014, incorporating corrigendum May 2016.

The start and finish of text introduced or altered by corrigendum is indicated in the text by tags. Text altered by IEC corrigendum May 2016 is indicated in the text by  $\boxed{AC_1}$   $\langle \overline{AC_1} \rangle$ .

The UK participation in its preparation was entrusted to Technical Committee PEL/69, Electric vehicles.

A list of organizations represented on this committee can be obtained on request to its secretary.

This publication does not purport to include all the necessary provisions of a contract. Users are responsible for its correct application.

© The British Standards Institution 2016. Published by BSI Standards Limited 2016

ISBN 978 0 580 94715 5

ICS 43.120

# Compliance with a British Standard cannot confer immunity from legal obligations.

This British Standard was published under the authority of the Standards Policy and Strategy Committee on 30 June 2014.

#### Amendments/corrigenda issued since publication

| Date         | Text affected                              |
|--------------|--|
| 31 July 2016 | Implementation of IEC corrigendum May 2016 |

# EUROPEAN STANDARD NORME EUROPÉENNE EUROPÄISCHE NORM

# EN 61851-23

May 2014

ICS 43.120

**English Version** 

## Electric vehicle conductive charging system -Part 23: DC electric vehicle charging station (IEC 61851-23:2014)

Système de charge conductive pour véhicules électriques -Partie 23: Borne de charge en courant continu pour véhicules électriques (CEI 61851-23:2014) Konduktive Ladesysteme für Elektrofahrzeuge - Teil 23: Gleichstromladestationen für Elektrofahrzeuge (IEC 61851-23:2014)

This European Standard was approved by CENELEC on 2014-04-15. CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration.

Up-to-date lists and bibliographical references concerning such national standards may be obtained on application to the CEN-CENELEC Management Centre or to any CENELEC member.

This European Standard exists in three official versions (English, French, German). A version in any other language made by translation under the responsibility of a CENELEC member into its own language and notified to the CEN-CENELEC Management Centre has the same status as the official versions.

CENELEC members are the national electrotechnical committees of Austria, Belgium, Bulgaria, Croatia, Cyprus, the Czech Republic, Denmark, Estonia, Finland, Former Yugoslav Republic of Macedonia, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, the Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland, Turkey and the United Kingdom.



European Committee for Electrotechnical Standardization Comité Européen de Normalisation Electrotechnique Europäisches Komitee für Elektrotechnische Normung

CEN-CENELEC Management Centre: Avenue Marnix 17, B-1000 Brussels

© 2014 CENELEC All rights of exploitation in any form and by any means reserved worldwide for CENELEC Members.

## Foreword

The text of document 69/272/FDIS, future edition 1 of IEC 61851-23, prepared by IEC/TC 69 "Electric road vehicles and electric industrial trucks" was submitted to the IEC-CENELEC parallel vote and approved by CENELEC as EN 61851-23:2014.

The following dates are fixed:

| • | latest date by which the document has<br>to be implemented at national level by<br>publication of an identical national            | (dop) | 2015-01-15 |
|---|--|-------|------------|
| • | standard or by endorsement<br>latest date by which the national<br>standards conflicting with the<br>document have to be withdrawn | (dow) | 2017-04-15 |

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CENELEC [and/or CEN] shall not be held responsible for identifying any or all such patent rights.

## Endorsement notice

The text of the International Standard IEC 61851-23:2014 was approved by CENELEC as a European Standard without any modification.

In the official version, for Bibliography, the following notes have to be added for the standards indicated:

| IEC 60364-7-722 | NOTE | Harmonised as EN 60364-7-722 (not modified). |
|-----------------|------|--|
| IEC 61851-21-2  | NOTE | Harmonised as en 61851-21-2 (not modified).  |

## Annex ZA

#### (normative)

# Normative references to international publications with their corresponding European publications

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

NOTE 1 When an International Publication has been modified by common modifications, indicated by (mod), the relevant EN/HD applies.

NOTE 2 Up-to-date information on the latest versions of the European Standards listed in this annex is available here: www.cenelec.eu

| Publication            | Year         | Title  | <u>EN/HD</u>  | Year         |
|------------------------|--------------|--|---------------|--------------|
| IEC 60364-5-54         | 2011         | Low-voltage electrical installations -<br>Part 5-54: Selection and erection of electrical<br>equipment - Earthing arrangements and<br>protective conductors  | HD 60364-5-54 | 2011         |
| IEC 60950-1 (mod)      | 2005         | Information technology equipment - Safety -<br>Part 1: General requirements  | EN 60950-1    | 2006         |
| +A1 (mod)<br>+A2 (mod) | 2009<br>2013 |  | +A1<br>+A2    | 2010<br>2013 |
| IEC 61140              |              | Protection against electric shock - Common aspects for installation and equipment  | EN 61140      |              |
| IEC 61439-1            | 2011         | Low-voltage switchgear and controlgear<br>assemblies -<br>Part 1: General rules  | EN 61439-1    | 2011         |
| IEC/TS 61479-1         | 2005         | Effects of current on human beings and livestock -<br>Part 1: General aspects  | -             | -            |
| IEC 61557-8            | -            | Electrical safety in low voltage distribution<br>systems up to 1 000 v a.c. And 1 500 v d.c<br>Equipment for testing, measuring or<br>monitoring of protective measures -<br>Part 8: insulation monitoring devices for it<br>systems | EN 61557-8    | -            |
| IEC 61558-1            | 2005         | Safety of power transformers, power supplies<br>reactors and similar products -<br>Part 1: General requirements and tests  | , EN 61558-1  | 2005         |
| IEC 61851-1            | 2010         | Electric vehicle conductive charging system -<br>Part 1: General requirements  | EN 61851-1    | 2011         |
| IEC 61851-24           | 2014         | Electric vehicle conductive charging system -<br>Part 24: Digital communication between a d.c<br>EV charging station and an electric vehicle for<br>control of d.c. charging   |               | 2013         |
| IEC 62052-11           | -            | Electricity metering equipment (AC) - General requirements, tests and test conditions - Part 11: Metering equipment  | EN 62052-11   | -            |
| IEC 62053-21           | -            | Electricity metering equipment (a.c.) -<br>Particular requirements -<br>Part 21: Static meters for active energy<br>(classes 1 and 2)  | EN 62053-21   | -            |

| Publication<br>IEC 62196-3 | <u>Year</u><br>- | <u>Title</u><br>Plugs, socket-outlets, and vehicle couplers -<br>conductive charging of electric vehicles -<br>Part 3: Dimensional compatibility and<br>interchangeability requirements for dedicated<br>d.c. and combined a.c./d.c. pin and contact-<br>tube vehicle couplers |    | <u>Year</u><br>- |
|----------------------------|------------------|--|----|------------------|
| ISO/IEC 15118-2            | -                | Road vehicles – Vehicle to grid<br>communication interface -<br>Part 2: Technical protocol description and<br>open systems interconnections (OSI) layer<br>requirements  | -  | -                |
| ISO/IEC 15118-3            | -                | Road vehicles - Vehicle to grid communicatio<br>interface -<br>Part 3 Physical layer requirements  | n- | -                |
| IEC/TS 61479-1             | 2005             | Effects of current on human beings and livestock -<br>Part 1: General aspects  | -  | -                |
| ISO 11898-1                | -                | Road vehicles - Controller area network<br>(CAN) -<br>Part 1: Data link layer and physical signalling  | -  | -                |
| DIN SPEC 70121             | -                | Electromobility - Digital communication<br>between a d.c. EV charging station and an<br>electric vehicle for control of d.c. charging in<br>the Combined Charging System   | -  | -                |

## CONTENTS

| 1  Scope   | INT  | RODUCTION   | 6  |
|--|------|---|----|
| 3  Terms and definitions   | 1    | Scope   | 7  |
| 4  General requirements  10    5  Rating of the supply a.c. voltage  10    6  General system requirement and interface.  10    7  Protection against electric shock  18    8  Connection between the power supply and the EV.  19    9  Specific requirements for vehicle coupler  20    10  Charging cable assembly requirements  21    11  EVSE requirements for d.c. EV charging station  21    102  Communication between EV and d.c. EV charging station  29    Annex AA (normative)  DC EV charging station of system A  33    Annex CB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system C (Combined charging system)  55    Annex DE (informative)  Typical d.c. charging systems  75    Bibliography  76  76    Figure 101 – Overvoltage protection in case of earth fault  16    Figure 102 – Measuring network of touch current weighted for perception or reaction  23    Figure 103 – Step response for constant value control  26    Figure 104 – Current ripple measurement equipment with capacitor <td< td=""><td>2</td><td>Normative references</td><td>7</td></td<>   | 2    | Normative references  | 7  |
| 5  Rating of the supply a.c. voltage   | 3    | Terms and definitions   | 8  |
| 6  General system requirement and interface  | 4    | General requirements  | 10 |
| 7  Protection against electric shock  18    8  Connection between the power supply and the EV.  19    9  Specific requirements for vehicle coupler.  20    10  Charging cable assembly requirements  21    11  EVSE requirements for d.c. EV charging station  24    102  Communication between EV and d.c. EV charging station  29    Annex AA (normative)  DC EV charging station of system A  33    Annex BB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system C (Combined charging system)  55    Annex DD (informative)  Typical d.c. charging systems  70    Annex EE (informative)  Typical configuration of d.c. charging system  75    Bibliography  76    Figure 101 – Overvoltage protection in case of earth fault  16    Figure 102 – Measuring network of touch current weighted for perception or reaction  23    Figure 103 – Step response for constant value control  26    Figure 104 – Current ripple measurement equipment with capacitor  27    Figure AA.1 – Overall schematic of system A station and EV  34    Figure AA.2 – Interface circuit for  | 5    | Rating of the supply a.c. voltage   | 10 |
| 8  Connection between the power supply and the EV.  19    9  Specific requirements for vehicle coupler.  20    10  Charging cable assembly requirements  21    11  EVSE requirements for d.c. EV charging station  24    102  Communication between EV and d.c. EV charging station  29    Annex AA (normative)  DC EV charging station of system A  33    Annex BB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system C (Combined charging system)  55    Annex DD (informative)  Typical d.c. charging systems  70    Annex EE (informative)  Typical configuration of d.c. charging system  75    Bibliography  76    Figure 101 – Overvoltage protection in case of earth fault  16    Figure 102 – Measuring network of touch current weighted for perception or reaction  23    Figure 103 – Step response for constant value control  26    Figure 104 – Current ripple measurement equipment with capacitor  27    Figure AA.1 – Overall schematic of system A station and EV  34    Figure AA.2 – Interface circuit for charging control of system A station  35    Figure AA.3 –  | 6    | General system requirement and interface  | 10 |
| 9  Specific requirements for vehicle coupler.  20    10  Charging cable assembly requirements  21    11  EVSE requirements  21    101  Specific requirements for d.c. EV charging station  24    102  Communication between EV and d.c. EV charging station  29    Annex AA (normative)  DC EV charging station of system A  33    Annex BB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system C (Combined charging system)  55    Annex DD (informative)  Typical d.c. charging systems  70    Annex EE (informative)  Typical configuration of d.c. charging system  75    Bibliography  76    Figure 101 – Overvoltage protection in case of earth fault  16    Figure 102 – Measuring network of touch current weighted for perception or reaction  23    Figure 103 – Step response for constant value control  26    Figure 104 – Current ripple measurement equipment with capacitor  27    Figure AA.1 – Overall schematic of system A station and EV  34    Figure AA.2 – Interface circuit for charging control of system A station  35    Figure AA.3 – Failure detection princi   | 7    | Protection against electric shock   | 18 |
| 10  Charging cable assembly requirements  21    11  EVSE requirements  21    101  Specific requirements for d.c. EV charging station  24    102  Communication between EV and d.c. EV charging station  29    Annex AA (normative)  DC EV charging station of system A  33    Annex BB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system C (Combined charging system)  55    Annex DD (informative)  Typical d.c. charging systems  70    Annex EE (informative)  Typical configuration of d.c. charging system  75    Bibliography  76    Figure 101 – Overvoltage protection in case of earth fault  16    Figure 102 – Measuring network of touch current weighted for perception or reaction  23    Figure 103 – Step response for constant value control  26    Figure 104 – Current ripple measurement equipment with capacitor  27    Figure AA.1 – Overall schematic of system A station and EV  34    Figure AA.2 – Interface circuit for charging control of system A station  35    Figure AA.3 – Failure detection principle by detection of d.c. leakage current  38    Figure AA.4 – Examp   | 8    | Connection between the power supply and the EV                                  | 19 |
| 11  EVSE requirements  21    101  Specific requirements for d.c. EV charging station  24    102  Communication between EV and d.c. EV charging station  29    Annex AA (normative)  DC EV charging station of system A  33    Annex BB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system B  47    Annex DD (informative)  DC EV charging systems  70    Annex EE (informative)  Typical d.c. charging systems  70    Annex EE (informative)  Typical configuration of d.c. charging system  75    Bibliography  76    Figure 101 - Overvoltage protection in case of earth fault  16    Figure 102 - Measuring network of touch current weighted for perception or reaction  23    Figure 103 - Step response for constant value control  26    Figure 104 - Current ripple measurement equipment with capacitor  27    Figure AA.1 - Overall schematic of system A station and EV  34    Figure AA.2 - Interface circuit for charging control of system A station  35    Figure AA.3 - Failure detection principle by detection of d.c. leakage current  38    Figure AA.4 - Example of vehicle connect   | 9    | Specific requirements for vehicle coupler                                       | 20 |
| 101  Specific requirements for d.c. EV charging station  24    102  Communication between EV and d.c. EV charging station  29    Annex AA (normative)  DC EV charging station of system A  33    Annex BB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system B  47    Annex DD (informative)  Typical d.c. charging systems  70    Annex EE (informative)  Typical configuration of d.c. charging system  75    Bibliography  76    Figure 101 - Overvoltage protection in case of earth fault  16    Figure 102 - Measuring network of touch current weighted for perception or reaction  23    Figure 103 - Step response for constant value control  26    Figure 104 - Current ripple measurement equipment with capacitor  27    Figure 105 - Maximum ratings for voltage dynamics  28    Figure AA.1 - Overall schematic of system A station and EV  34    Figure AA.2 - Interface circuit for charging control of system A station  35    Figure AA.3 - Failure detection principle by detection of d.c. leakage current  38    Figure AA.4 - Example of vehicle connector latch and lock monitoring circuit  40    Figure AA.   | 10   | Charging cable assembly requirements  | 21 |
| 102 Communication between EV and d.c. EV charging station  29    Annex AA (normative)  DC EV charging station of system A  33    Annex BB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system C (Combined charging system)  55    Annex DD (informative)  Typical d.c. charging systems  70    Annex EE (informative)  Typical configuration of d.c. charging system  75    Bibliography  76    Figure 101 – Overvoltage protection in case of earth fault  16    Figure 102 – Measuring network of touch current weighted for perception or reaction  23    Figure 103 – Step response for constant value control  26    Figure 104 – Current ripple measurement equipment with capacitor  27    Figure 105 – Maximum ratings for voltage dynamics  28    Figure AA.1 – Overall schematic of system A station and EV  34    Figure AA.2 – Interface circuit for charging control of system A station  35    Figure AA.3 – Failure detection principle by detection of d.c. leakage current  38    Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit  40    Figure AA.5 – State transition diagram of charging process for system A  43               | 11   | EVSE requirements   | 21 |
| Annex AA (normative)  DC EV charging station of system A   | 101  | Specific requirements for d.c. EV charging station                              | 24 |
| Annex BB (normative)  DC EV charging station of system B  47    Annex CC (normative)  DC EV charging station of system C (Combined charging system)  55    Annex DD (informative)  Typical d.c. charging systems  70    Annex EE (informative)  Typical configuration of d.c. charging system  75    Bibliography  76    Figure 101 – Overvoltage protection in case of earth fault  16    Figure 102 – Measuring network of touch current weighted for perception or reaction  23    Figure 103 – Step response for constant value control  26    Figure 104 – Current ripple measurement equipment with capacitor  27    Figure 105 – Maximum ratings for voltage dynamics  28    Figure AA.1 – Overall schematic of system A station and EV  34    Figure AA.2 – Interface circuit for charging control of system A station  35    Figure AA.3 – Failure detection principle by detection of d.c. leakage current  38    Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit  40    Figure AA.5 – State transition diagram of charging process for system A  43    Figure AA.6 – Sequence diagram of system A  44    Figure AA.6 – Charging current value requested by the vehicle  45    Figure AA.7 – Chargi | 102  | Communication between EV and d.c. EV charging station                           | 29 |
| Annex CC (normative)  DC EV charging station of system C (Combined charging system)    55  Annex DD (informative)  Typical d.c. charging systems    70  Annex EE (informative)  Typical configuration of d.c. charging system    75  Bibliography  | Ann  | ex AA (normative) DC EV charging station of system A                            | 33 |
| system)55Annex DD (informative) Typical d.c. charging systems70Annex EE (informative) Typical configuration of d.c. charging system75Bibliography76Figure 101 – Overvoltage protection in case of earth fault16Figure 102 – Measuring network of touch current weighted for perception or reaction23Figure 103 – Step response for constant value control26Figure 104 – Current ripple measurement equipment with capacitor27Figure 105 – Maximum ratings for voltage dynamics28Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A44Figure AA.6 – Sequence diagram of system A44Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46  | Ann  | ex BB (normative) DC EV charging station of system B                            | 47 |
| Annex EE (informative)Typical configuration of d.c. charging system75Bibliography76Figure 101 – Overvoltage protection in case of earth fault16Figure 102 – Measuring network of touch current weighted for perception or reaction23Figure 103 – Step response for constant value control26Figure 104 – Current ripple measurement equipment with capacitor27Figure 105 – Maximum ratings for voltage dynamics28Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A44Figure AA.6 – Sequence diagram of system A44Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46  | Ann  |   | 55 |
| Bibliography76Figure 101 – Overvoltage protection in case of earth fault16Figure 102 – Measuring network of touch current weighted for perception or reaction23Figure 103 – Step response for constant value control26Figure 104 – Current ripple measurement equipment with capacitor27Figure 105 – Maximum ratings for voltage dynamics28Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A43Figure AA.6 – Sequence diagram of system A44Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46   | Ann  | ex DD (informative) Typical d.c. charging systems                               | 70 |
| Figure 101 – Overvoltage protection in case of earth fault16Figure 102 – Measuring network of touch current weighted for perception or reaction23Figure 103 – Step response for constant value control26Figure 104 – Current ripple measurement equipment with capacitor27Figure 105 – Maximum ratings for voltage dynamics28Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A43Figure AA.6 – Sequence diagram of system A44Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46   | Ann  | ex EE (informative) Typical configuration of d.c. charging system               | 75 |
| Figure 102 – Measuring network of touch current weighted for perception or reaction23Figure 103 – Step response for constant value control26Figure 104 – Current ripple measurement equipment with capacitor27Figure 105 – Maximum ratings for voltage dynamics28Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A43Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46   | Bibl | iography  | 76 |
| Figure 102 – Measuring network of touch current weighted for perception or reaction23Figure 103 – Step response for constant value control26Figure 104 – Current ripple measurement equipment with capacitor27Figure 105 – Maximum ratings for voltage dynamics28Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A43Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46   |      |   |    |
| Figure 103 – Step response for constant value control26Figure 104 – Current ripple measurement equipment with capacitor27Figure 105 – Maximum ratings for voltage dynamics28Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A43Figure AA.6 – Sequence diagram of system A44Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46  | Figu | re 101 – Overvoltage protection in case of earth fault                          | 16 |
| Figure 104 - Current ripple measurement equipment with capacitor27Figure 105 - Maximum ratings for voltage dynamics28Figure AA.1 - Overall schematic of system A station and EV34Figure AA.2 - Interface circuit for charging control of system A station35Figure AA.3 - Failure detection principle by detection of d.c. leakage current38Figure AA.4 - Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 - State transition diagram of charging process for system A43Figure AA.6 - Sequence diagram of system A44Figure AA.7 - Charging current value requested by the vehicle45Figure AA.8 - Output response performance of d.c. EV charging station46   | Figu | re 102 – Measuring network of touch current weighted for perception or reaction | 23 |
| Figure 105 – Maximum ratings for voltage dynamics28Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A43Figure AA.6 – Sequence diagram of system A44Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46   | Figu | re 103 – Step response for constant value control                               | 26 |
| Figure AA.1 – Overall schematic of system A station and EV34Figure AA.2 – Interface circuit for charging control of system A station35Figure AA.3 – Failure detection principle by detection of d.c. leakage current38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit40Figure AA.5 – State transition diagram of charging process for system A43Figure AA.6 – Sequence diagram of system A44Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46  | Figu | re 104 – Current ripple measurement equipment with capacitor                    | 27 |
| Figure AA.2 – Interface circuit for charging control of system A station.35Figure AA.3 – Failure detection principle by detection of d.c. leakage current.38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit.40Figure AA.5 – State transition diagram of charging process for system A.43Figure AA.6 – Sequence diagram of system A.44Figure AA.7 – Charging current value requested by the vehicle.45Figure AA.8 – Output response performance of d.c. EV charging station.46   | Figu | re 105 – Maximum ratings for voltage dynamics                                   | 28 |
| Figure AA.3 – Failure detection principle by detection of d.c. leakage current.38Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit.40Figure AA.5 – State transition diagram of charging process for system A.43Figure AA.6 – Sequence diagram of system A.44Figure AA.7 – Charging current value requested by the vehicle.45Figure AA.8 – Output response performance of d.c. EV charging station.46  | Figu | re AA.1 – Overall schematic of system A station and EV                          | 34 |
| Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit   | Figu | re AA.2 – Interface circuit for charging control of system A station            | 35 |
| Figure AA.4 – Example of vehicle connector latch and lock monitoring circuit   | Figu | re AA.3 – Failure detection principle by detection of d.c. leakage current      | 38 |
| Figure AA.5 – State transition diagram of charging process for system A43Figure AA.6 – Sequence diagram of system A44Figure AA.7 – Charging current value requested by the vehicle45Figure AA.8 – Output response performance of d.c. EV charging station46  | -    |   |    |
| Figure AA.6 – Sequence diagram of system A   | -    |   |    |
| Figure AA.7 – Charging current value requested by the vehicle  | -    |   |    |
| Figure AA.8 – Output response performance of d.c. EV charging station  |      |   |    |
|  |      |   |    |
|  | -    | re BB.1 – Schematic diagram for basic solution for d.c. charging system         |    |
| Figure BB.2 – Sequence diagram of charging process   | -    |   |    |
| Figure BB.3 – Operation flow chart of start charging   | -    |   |    |
| Figure BB.4 – Operation flow chart of stop charging  | -    |   |    |
| Figure CC.1 – Sequence diagram for normal start up   | -    |   |    |

| Figure CC.2 – Sequence diagram and description for normal shutdown                           | 59 |
|--|----|
| Figure CC.3 – Sequence diagram for d.c. supply initiated emergency shutdown                  | 61 |
| Figure CC.4 – Sequence diagram for EV initiated emergency shutdown                           | 63 |
| Figure CC.5 – Special components for configurations CC and EE coupler                        | 66 |
| Figure CC.6 – System schematics of combined d.c. charging system                             | 68 |
| Figure D.1 – Example of typical isolated system  | 70 |
| Figure D.2 – Example of typical non-isolated system  | 71 |
| Figure D.3 – Example of simplified isolated system   | 71 |
| Figure D.4 – Example of DC mains system  | 72 |
| Figure E.1 – Typical configuration of d.c. charging system                                   | 75 |
|  |    |
| Table 101 – Current ripple limit of d.c. EV charging station                                 | 27 |
| Table 102 – Charging state of d.c. EV charging station                                       | 30 |
| Table 103 – Charging control process of d.c. EV charging station at system action level      | 31 |
| Table AA.1 – Definition of symbols in Figure AA.1 and Figure AA.2                            | 36 |
| Table AA.2 – Parameters and values for interface circuit in Figure AA.2                      | 37 |
| Table AA.3 – Principle of fault protection   | 37 |
| Table AA.4 – Requirements for earth fault monitoring   | 39 |
| Table AA.5 – Recommended specification of charging current requested by the vehicle          | 45 |
| Table AA.6 – Requirements for the output response performance of d.c. EV charging            |    |
| station  |    |
| Table BB.1 – Definitions of charging states  |    |
| Table BB.2 – Recommended parameters of d.c. charging security system                         | 51 |
| Table CC.1 – DC couplers and maximum system output voltage for combined charging      system | 55 |
| Table CC.2 – Definition of proximity resistor for configurations DD and FF                   | 55 |
| Table CC.3 – Sequence description for normal start up  | 58 |
| Table CC.4 – Sequence description for normal shutdown  | 60 |
| Table CC.5 – Definition and description of symbols / terms                                   | 69 |
| Table D.1 – Example for categories of d.c. supply system to electric vehicles                | 73 |
| Table D.2 – Typical voltage ranges for isolated d.c. EV charging stations                    | 74 |

#### INTRODUCTION

The introduction and commercialisation of electric vehicles has been accelerated in the global market, responding to the global concerns on  $CO_2$  reduction and energy security. Concurrently, the development of charging infrastructure for electric vehicles has also been expanding. As a complement to the a.c. charging system, d.c. charging is recognized as an effective solution to extend the available range of electric vehicles. The international standardization of charging infrastructure is indispensable for the diffusion of electric vehicles, and this standard is developed for the manufacturers' convenience by providing general and basic requirements for d.c. EV charging stations for conductive connection to the vehicle.

### ELECTRIC VEHICLE CONDUCTIVE CHARGING SYSTEM -

### Part 23: DC electric vehicle charging station

#### 1 Scope

This part of IEC 61851, together with IEC 61851-1:2010, gives the requirements for d.c. electric vehicle (EV) charging stations, herein also referred to as "DC charger", for conductive connection to the vehicle, with an a.c. or d.c. input voltage up to 1 000 V a.c. and up to 1 500 V d.c. according to IEC 60038.

NOTE 1 This standard includes information on EV for conductive connection, but limited to the necessary content for describing the power and signaling interface.

This part covers d.c. output voltages up to 1 500 V.

Requirements for bi-directional power flow are under consideration.

NOTE 2 Typical diagrams and variation of d.c. charging systems are shown in Annex DD.

This standard does not cover all safety aspects related to maintenance.

This part specifies the d.c. charging systems A, B and C as defined in Annexes AA, BB and CC.

NOTE 3 Typical configuration of d.c. EV charging system is shown in Annex EE.

EMC requirements for d.c. EV charging stations are defined in IEC 61851-21-2.

This standard provides the general requirements for the control communication between a d.c. EV charging station and an EV. The requirements for digital communication between d.c. EV charging station and electric vehicle for control of d.c. charging are defined in IEC 61851-24.

#### 2 Normative references

This clause of Part 1 is applicable except as follows:

Addition:

IEC 60364-5-54:2011, Low-voltage electrical installations – Part 5-54: Selection and erection of electrical equipment – Earthing arrangements and protective conductors

IEC/TS 60479-1:2005, Effects of current on human beings and livestock - Part 1: General aspects

IEC 60950-1:2005, Information technology equipment - Safety - Part 1: General requirements Amendment 1:2009 Amendment 2:2013

IEC 61140, Protection against electric shock – Common aspects for installation and equipment